

## Features

- ❑ **Motors supported:**
  - Panasonic A and S series
  - Brushless 60/120° commutated
  - Brush-commutated (DC) motors
- ❑ **Up to 20A peak, 12A continuous output current**
- ❑ **12 to 90VDC power supply**
- ❑ **Separate motor and logic power supply terminals**
- ❑ **Path point buffer for coordinated motion control**
- ❑ **30/60/120/240 Hz point rate**
- ❑ **32-bit position, velocity, acceleration, 16-bit PID filter gain values**
- ❑ **Comprehensive motor output short-circuit protection:**
  - Output to output
  - Output to ground
  - Output to power
- ❑ **Adjustable motor current limit**
- ❑ **Over/under voltage shutdown**
- ❑ **Overheating protection**
- ❑ **Hardware Stop Input**
- ❑ **Forward and reverse over travel inputs**
- ❑ **Communication speed 19.2 - 115.2 KBps**
- ❑ **Servo rate 2 kHz**
- ❑ **PWM frequency 20 kHz**
- ❑ **Command rate up to 1000/sec**
- ❑ **Small footprint (5" x 3.3" x 0.85")**



## Description

LS-173CMWP is a version of the LS-173CM, with separate motor and logic power supply terminals, and replacement for LS-174WP. Motor power supply can be switched OFF without affecting the encoder reading and device communication. LS-173CMWP is a single-axis motion controller with integrated servo amplifier designed for applications using Panasonic A and S series motors, standard brushless motors and brush-commutated motors up to 1 HP. Trapezoidal brushless motor commutation is performed. Up to 31 intelligent servo drives can be controlled over a multi-drop full duplex RS-485 network in a distributed motion control environment. Standard RJ-45 connectors and commercially available cables are used for daisy chaining of the modules.

LS-173CMWP is equipped with various safety features such as short circuit protection for the motor and amplifier, over travel switch inputs, hardware stop input, over/under voltage shutdown and encoder presence control. The maximum motor output current can be limited by setting of dip-switches or by software.

**TECHNICAL SPECIFICATIONS** rated at 25°C ambient, POWER (+)=60VDC, Load=250μH motor

POWER SUPPLY VOLTAGE MOTOR PWR LOGIC PWR	12 to 90 V DC, 100V Absolute Maximum 12 to 90 V DC, 100V Absolute Maximum
POWER CONSUMPTION (LOGOC PWR)	2.5W at 24V
MAX MOTOR OUTPUT CURRENT LS-173CMWP-1210 Peak / Continuous LS-173CMWP-2010 Peak / Continuous	12A/8A 20A/12A
MAX MOTOR OUTPUT VOLTAGE	$V_{out} = 0.96(\text{POWER (+)}) - 0.17(I_{out})$
MIN LOAD INDUCTANCE	200μH
PWM SWITCHING FREQUENCY	19,512 KHz
SERVO RATE	0.512 msec
SERIAL BAUD RATE	19.2 – 115.2 Kbps
OPEN COLLECTOR BRAKE OUTPUT Max voltage applied to output Max current	48V 0.3A
INPUTS Encoder & Commutation Digital Inputs	TTL with 1K pull-up to 5V LO min=-1V, HI max=48V
ENCODER	Quadrature with index or Panasonic encoder mode
COMMUTATION	Hall sensors 60/120° or Panasonic
INDICATORS Orange Green	Power 'ok' (ORANGE and GREEN leds are ON when the Servo 'on' Power OK' and the device is not initialized)
PROTECTION Short circuit  Overheating shut off	Motor output to motor output Motor output to POWER GND Motor output to POWER (+) Activated at 80 °C
FIRE-SAFETY Internal fuse LS-173CMWP-1210 LS-173CMWP-2010	Quick blow 10A 15A
POWER DISSIPATION (max)	30W
THERMAL REQUIREMENTS Storage temperature range Operating temperature range	-30 to +85 °C 0 to 45 °C
MECHANICAL Size Weight	L=5.00", H=3.30", D=0.85" 0.55lb. (250gr.)
MATING CONNECTORS Power & Motor Inputs & Outputs Encoder & Commutator Communication	Magnum EM2565-06-VL or Phoenix MSTB2.5/6-ST-5.08 Molex 22-01-3077 housing with 08-50-0114 pins (7 pcs.) Molex 22-01-3107 housing with 08-50-0114 pins (10 pcs.) 8 pin RJ-45

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Technical drawing of the LS-173CMWP-1210 servo drive, showing front and side views with dimensions and pin configurations.

**Front View Dimensions:**

- Overall Width: 5.000
- Overall Height: 3.300
- Top Mounting Flange Width: 0.165
- Mounting Hole Spacing (Left): 0.750
- Mounting Hole Spacing (Right): 0.165
- Internal Component Height: 2.000
- Terminal Block Height: 0.850
- Terminal Block Spacing: 0.500

**Side View Dimensions:**

- Overall Height: 3.570 max

**Front View Details:**

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LOGOSOL

AC/DC INTELLIGENT SERVO DRIVE FOR COORDINATED CONTROL LS-173CMWP-1210

CE

HOST - CN5 SLAVE - CN4 ENCODER AND COMPUTATOR - CN3 I/O CONTROL - CN2 MOTOR AND POWER - CN1

NETWORK IN NETWORK OUT

8 - A in 7 - A in 6 - TX 3 - TX 1 - 5V 2 - GND

8 - A out 7 - A out 6 - RX 3 - TX 4 - TX 1 - N.C. 2 - GND

1 - GND 2 - Z 3 - A 4 - B 5 - B 6 - 5V 7 - 8 9 - 10 GND IN 11 - GND 12 - GND 13 - GND 14 - GND 15 - GND 16 - GND 17 - BRAKE OUT 18 - MOTOR AC1 (U) or DCL(+) 19 - MOTOR AC2 (V) or DCL(-) 20 - MOTOR AC3 (W) or N.C. 21 - POWER GND 22 - LOGIC PWR(+12 to 90DC 23 - MOTOR PWR(+12 to 90DC

Diagram illustrating the internal components of the 1000 Series Servo Motor, showing the motor housing and internal wiring connections.

**Top View Labels:**

- CN5 NETWORK INPUT (HOST)
- CN4 NETWORK OUTPUT (SLAVE)
- MOTOR
- POWER
- CN1
- CN2 I/O CONTROL
- CN3 ENCODER AND COMMUTATOR

**Bottom View Labels:**

- CONFIGURATION SWITCHES
- TERMINATORS
- CURRENT LIMIT
- MODE

PART NUMBER	MODEL	DESCRIPTION
912173053	LS-173CMWP-1210	Intelligent Servo Drive for Coordinated Control 12A/8A /100V
912173054	LS-173CMWP-2010	Intelligent Servo Drive for Coordinated Control 20A/12A /100V
230601004	LS-173-CN	Mating connector kit
230601017	PAN-AS-CN	Mating connector kit for Panasonic A and S series motors
230601027	PAN-ASB-CN	Mating connector kit for Panasonic A and S series motors with brake

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# LOGOSOL

AC/DC INTELLIGENT SERVO DRIVE FOR COORDINATED CONTROL LS-173CMWP-1210

CE

- Mode Sw.2  
 - Mode Sw.1  
 - A  
 - B  
 - C  
 - D  
 - T  
 - output  
 - output  
 on  
 DP SW

HOST - CN5  
 SLAVE - CN4  
 ENCODER AND COMMUTATOR - CN3  
 I/O CONTROL - CN2  
 MOTOR AND POWER - CN1

NETWORK IN  
 NETWORK OUT

-7 -A in  
 -5 -RX  
 -3 -TX  
 -1 +SV

-7 -A out  
 -5 -RX  
 -3 -TX  
 -1 NC

P-Mode	DFT Enc	Hall
+RX	-Z	S3
-B	-B	S2
-A	-A	S1

-1 GND  
 -2 +V  
 -3 -A  
 -4 +SV  
 -5 +B  
 -6 +SV  
 -7  
 -8  
 -9  
 -10 GND  
 -11 STP IN  
 -12 GND  
 -13 LIMIT 1 (REVERSE)  
 -14 GND  
 -15 LIMIT 2 (FORWARD)  
 -16 GND  
 -17 BRAKE OUT  
 -18 MOTOR ACT (U) or DC(+)

-19 MOTOR ACT2 (V) or DC(-)  
 -20 MOTOR ACT3 (W) or N.C.  
 -21 POWER GND  
 -22 LOGIC PWR(+12 to 90VDC)  
 -23 MOTOR PWR(+12 to 90VDC)

SW	SIGNAL	DESCRIPTION	FACTORY SETTING
1	T-output	Transmit line terminator	off
2	T-input	Receive line terminator	off
3	D	Current limit switch	off
4	C	Current limit switch	on
5	B	Current limit switch	on
6	A	Current limit switch	on
7	Mode Sw1	Mode select switch	on
8	Mode Sw2	Mode select switch	on

PIN	SIGNAL	DESCRIPTION
1	MOTOR PWR(+) 12 to 90VDC	12 to 90V motor power supply, positive terminal
2	LOGIC PWR(+) 12 to 90VDC	12 to 90V logic power supply, positive terminal
3	POWER GND	Power supply ground
4	MOTOR AC3 (W) or NC	Output to motor Phase 3 terminal for brushless motors Phase W for Panasonic A and S series motors Not connected for brush motors
5	MOTOR AC2 (V) or DC (-)	Output to motor Phase 2 terminal for brushless motors Phase V for Panasonic A and S series motors Negative terminal for brush motors
6	MOTOR AC1 (U) or DC (+)	Output to motor Phase 1 terminal for brushless motors Phase U for Panasonic A and S series motors Positive terminal for brush motors

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**CN2 – I/O CONTROL**

PIN	SIGNAL	DESCRIPTION
1	STP IN	Stop input (disables the drive)
2	GND*	Signal ground
3	LIMIT 1 (REVERSE)	Over travel input
4	GND*	Signal ground
5	LIMIT 2 (FORWARD)	Over travel input
6	GND*	Signal ground
7	BRAKE OUT	Brake output. Open collector output 48V/0.3A

**CN3 – ENCODER AND COMMUTATOR**

PIN	SIGNAL	DESCRIPTION
1	GND*	Encoder ground
2	+Z	Encoder index
3	+A	Encoder phase A
4	+5V**	Encoder power supply
5	+B	Encoder phase B
6	+5V**	Commutator power supply
7	S1	Hall input #1 for Hall mode
	-A	Encoder phase –A for DC brush motor (differential encoder)
	-A	Encoder phase –A for Panasonic A and S series motors
8	S2	Hall input #2 for Hall mode
	-B	Encoder phase –B for DC brush motor (differential encoder)
	-B	Encoder phase –B for Panasonic A and S series motors
9	S3	Hall input #3
	-Z	Encoder phase –Z for DC brush motor (differential encoder)
	+RX	Hall data for Panasonic A and S series motors
10	GND*	Commutator ground

**CN4 – NETWORK OUT (SLAVE)**

PIN	SIGNAL	DESCRIPTION
1	N.C.	Not connected
2	GND*	Interface ground
3	+TX	(+) Transmit data
4	-TX	(-) Transmit data
5	-RX	(-) Receive data
6	+RX	(+) Receive data
7	-A out	(-) Address output
8	+A out	(+) Address output

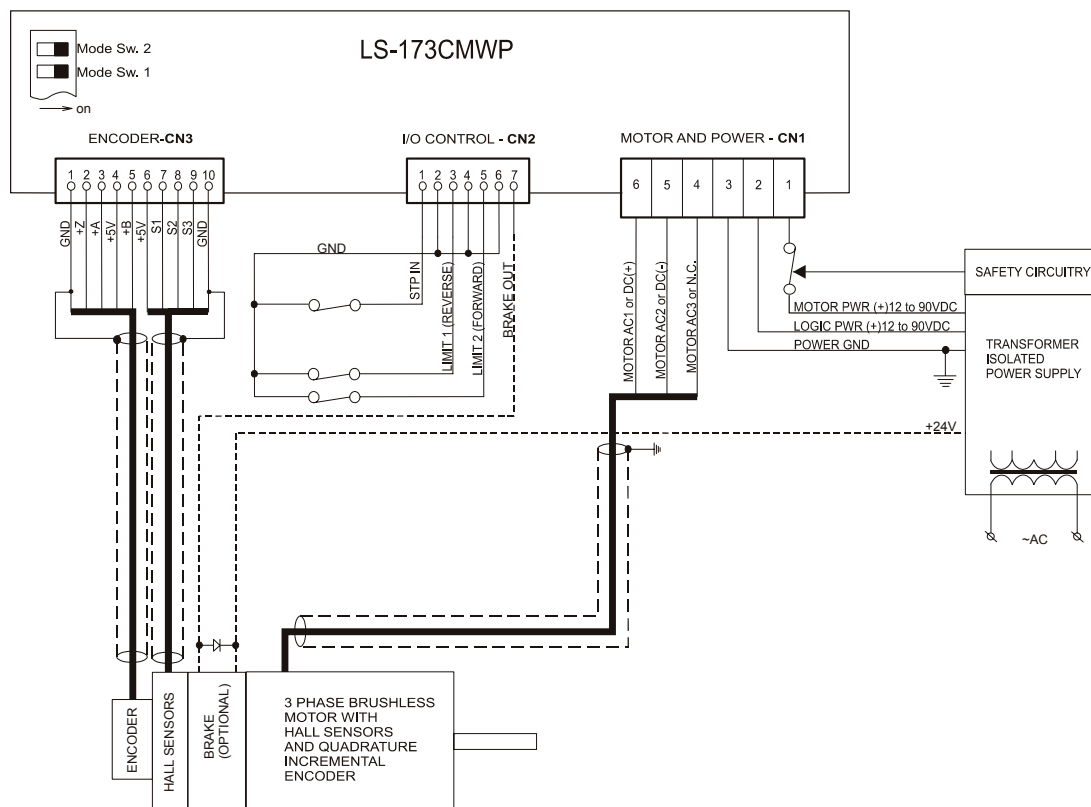
**CN5 – NETWORK IN (HOST)**

PIN	SIGNAL	DESCRIPTION
1	+5V**	RS-232 adapter power supply
2	GND*	Interface ground
3	+TX	(+) Transmit data
4	-TX	(-) Transmit data
5	-RX	(-) Receive data
6	+RX	(+) Receive data
7	-A in	(-) Address input
8	+A in	(+) Address input

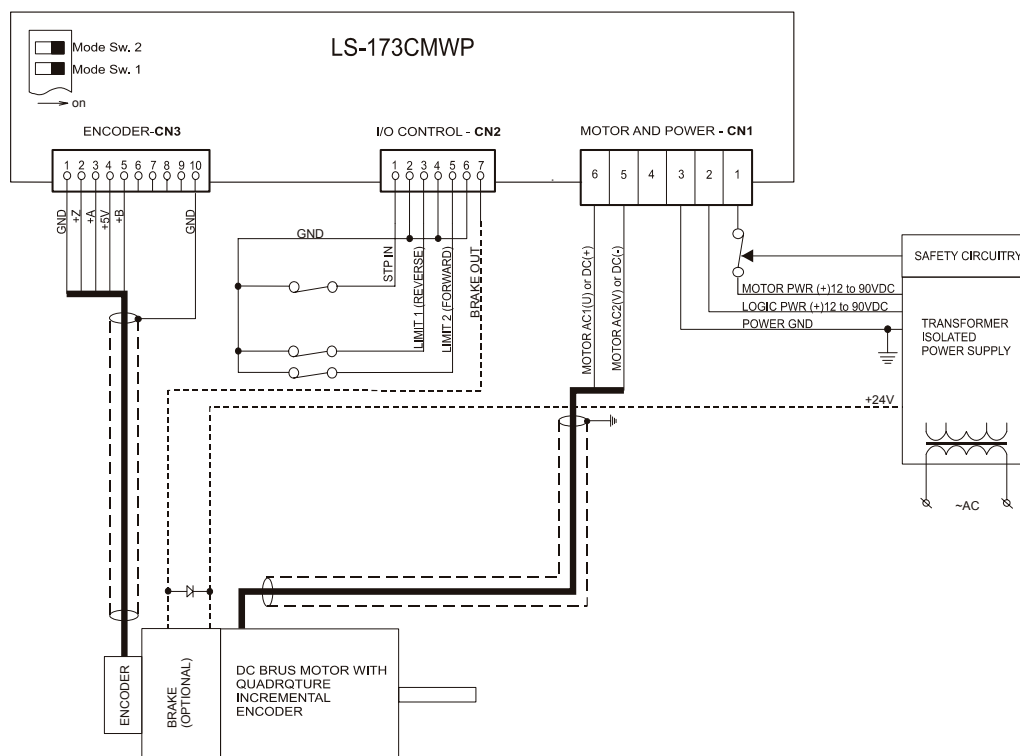
\* POWER GND and GND are electrically connected. Drive Case is isolated from drive circuitry and can be grounded externally.

\*\*200mA Max current for all three outputs combined.

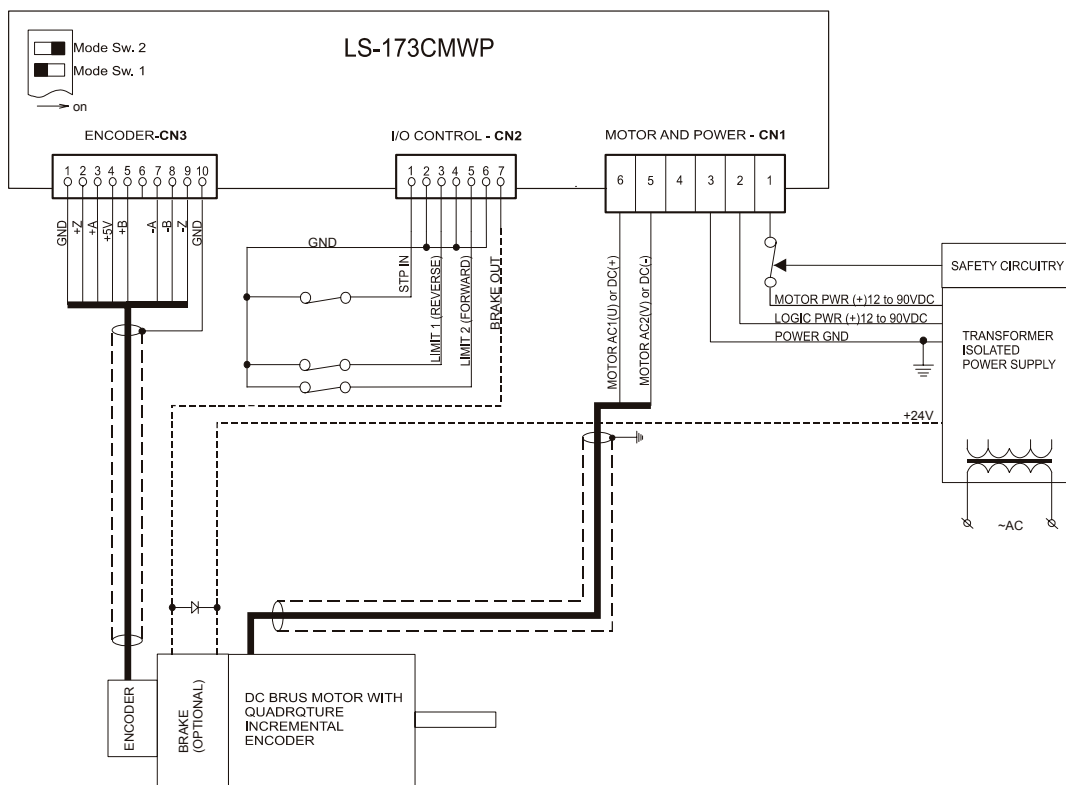
## SAMPLE APPLICATION using Brushless motor



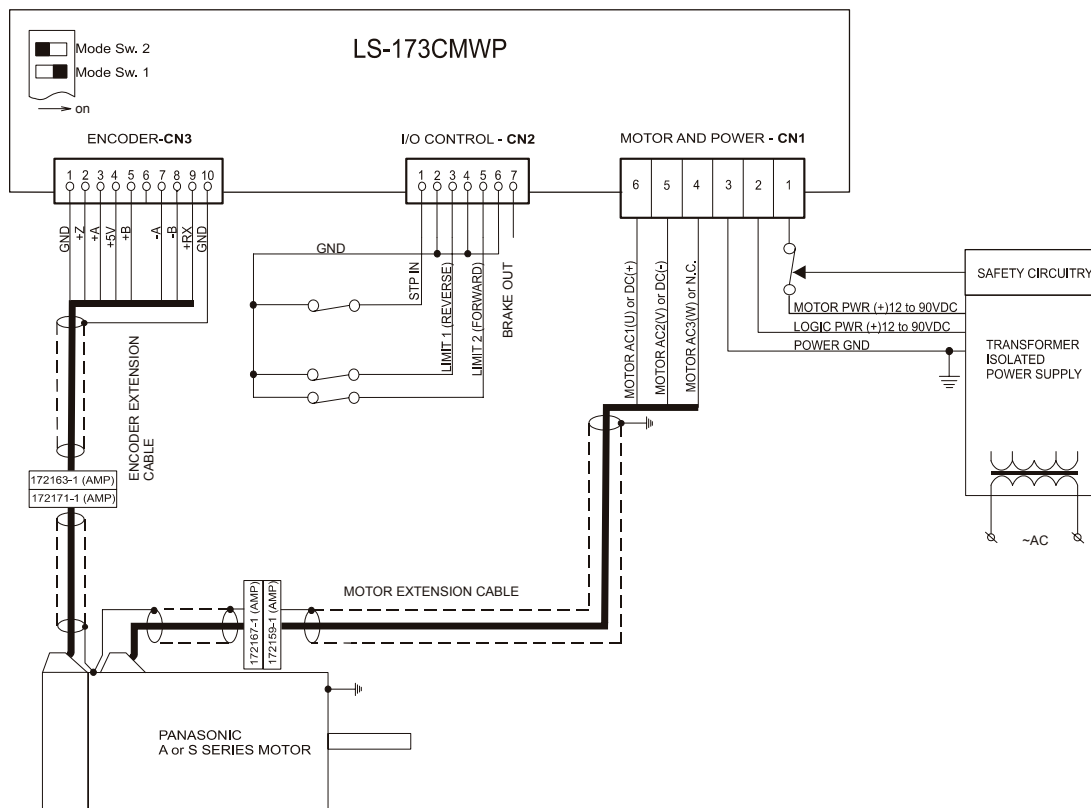
## SAMPLE APPLICATION using DC (brush) motor with single ended encoder



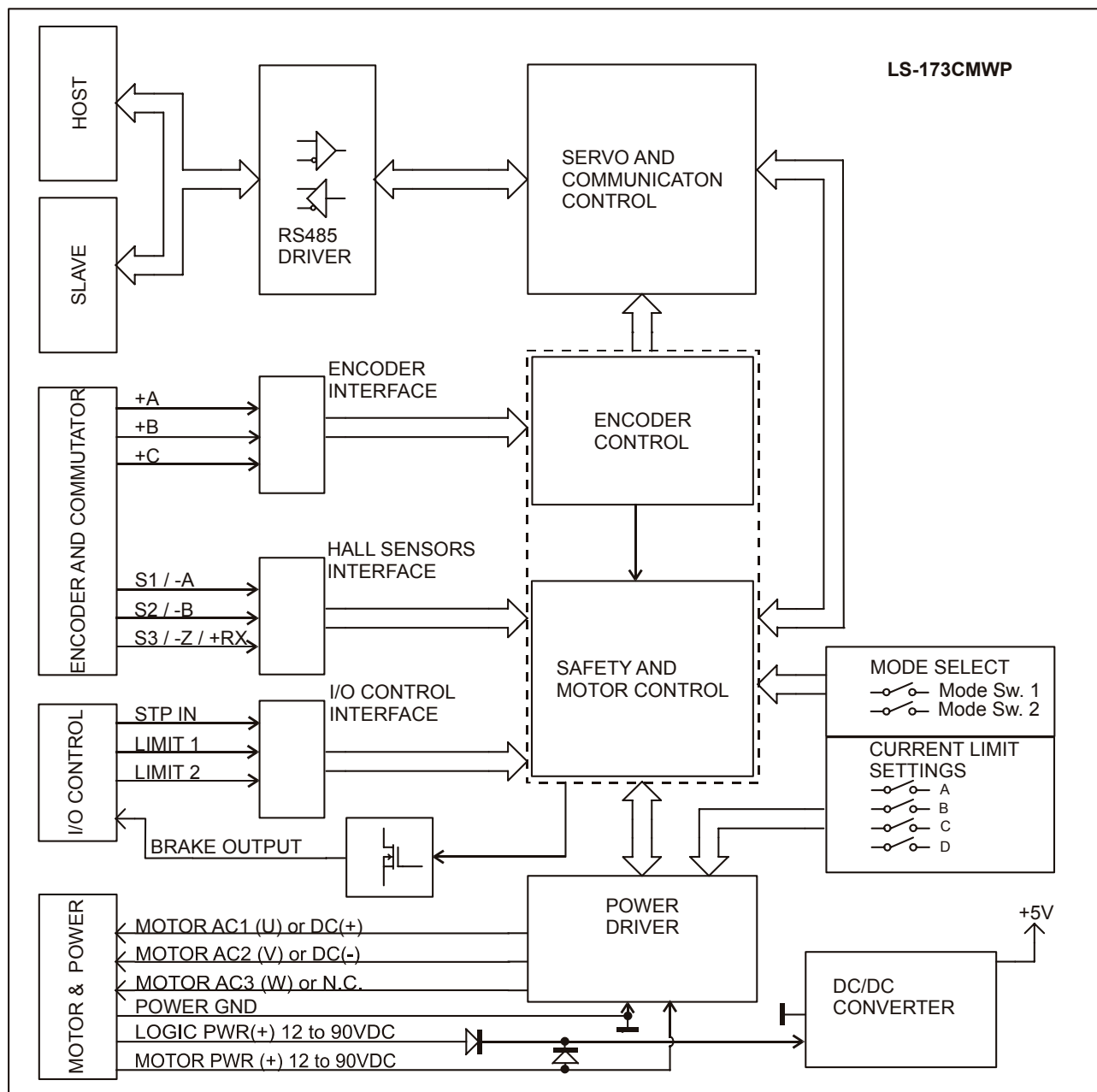
## SAMPLE APPLICATION using DC (brush) motor with differential encoder



## SAMPLE APPLICATION using Panasonic A or S series motor



## LS-173CMWP functional diagram



### For addition information regarding:

- Architecture;
- Safety features;
- Theory of operation;
- Commands description;
- Software examples;

**Refer to:** [LS-173CM Intelligent Servo Drive for Coordinated Control](#).